

# Grammar Implementation: XMG

## XMG Tutorial

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# Defining abstractions

## Classes allow to:

- Control the scope of variables
- Make (parametrized) abstractions

## Examples (just headers):

```
1 class kicked_the_bucket
2 import nx0Vnx1[]
3 declare ?X0 ?X1
```

```
1 class nx0Vnx1
2 export ?S ?NP_Subj ?VP ?V ?NP_Obj
3 declare ?S ?NP_Subj ?VP ?V ?NP_Obj ?X0 ?X1
```

# Defining abstractions

```
1 class Intransitive
2 declare ?S ?NP ?VP ?V
3 {
4   <syn>{
5     node ?S [cat=s];
6     node ?VP [cat=vp];
7     node ?V (mark=anchor) [cat=v];
8     node ?NP (mark=subst) [cat=n];
9     ?S -> ?VP; ?VP -> ?V;
10    ?S -> ?NP; ?NP >> ?VP
11  }
12 }
```

# Using abstractions

Classes can be used by other classes by two means:

- Importing the class in the header: all the (exported) variables are added to the scope, all the constraints from the class are added to the current set of constraints
- Calling the class in the body: variables are not added to the scope

Calling classes has two advantages:

- alternatives are possible (disjunction)
- it allows to use parameters

Examples:

```
1 CanObj[] | RelObj[]
```

```
1 ?C=Class[?X]
```

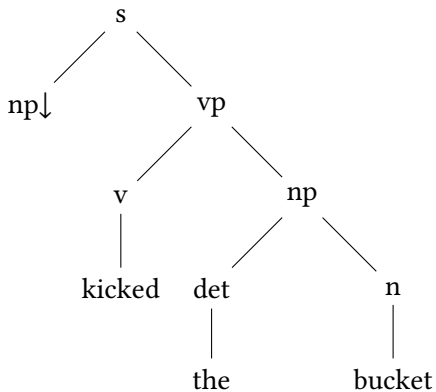
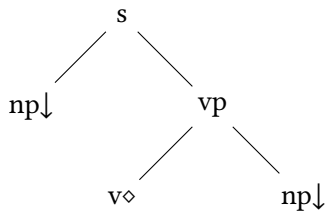
## Classes: examples (1)

```
1  class a
2  export ?A
3  declare ?A ?S
4  {
5    <syn>{
6      ?S -> ?A
7    }
8  }
9
10 class b
11 import a[]
12 declare ?B
13 {
14   <syn>{
15     ?B -> ?A
16   }
17 }
```

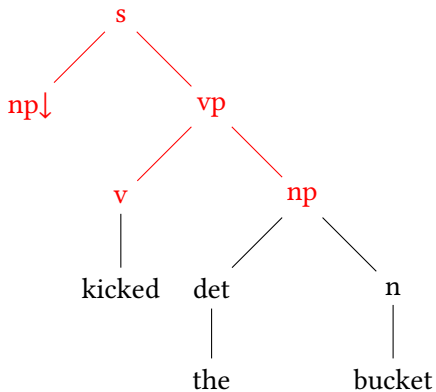
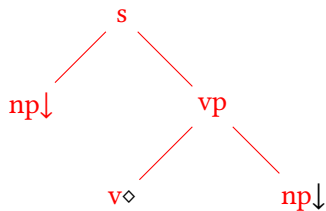
## Classes: examples (2)

```
1  class a
2  export ?S
3  declare ?A ?S
4  {
5    <syn>{
6      ?S -> ?A
7    }
8  }
9
10 class b
11 import a[]
12 declare ?A
13 {
14   <syn>{
15     ?S -> ?A
16   }
17 }
```

## Redundancy

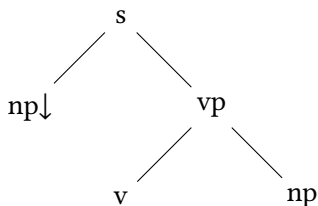


# Redundancy



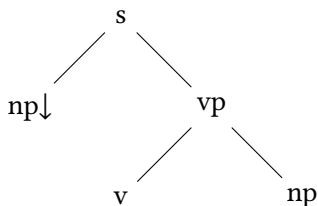


## First step: a generic tree fragment for transitive verbs



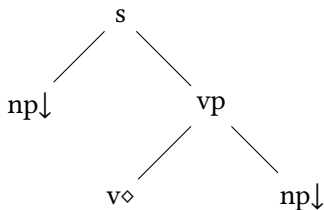
```
1 class nx0Vnx1
2 export ?S ?NP_Subj ?VP ?V ?NP_Obj
3 declare ?S ?NP_Subj ?VP ?V ?NP_Obj
4 {
5   <syn>{
6     node ?S [cat=s] {
7       node ?NP_Subj (mark=subst) [cat=np]
8       node ?VP [cat=vp] {
9         node ?V [cat=v]
10        node ?NP_Obj [cat=np] }}
11   }
12 }
```

## First step: a generic tree fragment for transitive verbs



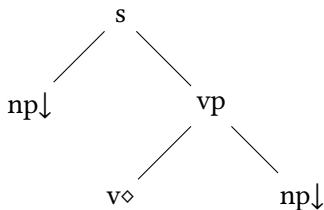
```
1 class nx0Vnx1
2 export ?S ?NP_Subj ?VP ?V ?NP_Obj
3 declare ?S ?NP_Subj ?VP ?V ?NP_Obj
4 {
5   <syn>{
6     node ?S [cat=s] {
7       node ?NP_Subj (mark=subst) [cat=np]
8       node ?VP [cat=vp] {
9         node ?V [cat=v]
10        node ?NP_Obj [cat=np] }}
11   }
12 }
```

## Standard tree for transitive verbs



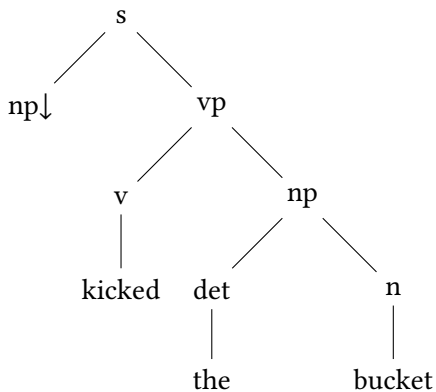
```
1 class kick
2 import nx0Vnx1[]
3 {
4   <syn>{
5     node ?V (mark=anchor);
6     node ?NP_Obj (mark=subst)
7   }
8 }
```

## Standard tree for transitive verbs



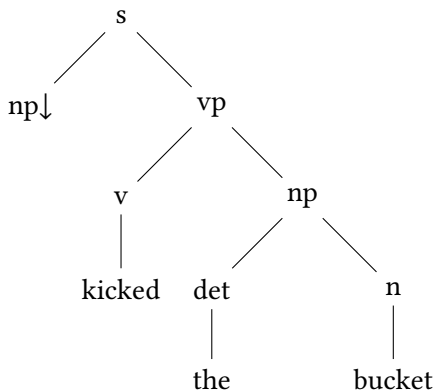
```
1 class kick
2 import nx0Vnx1[]
3 {
4   <syn>{
5     node ?V (mark=anchor);
6     node ?NP_Obj (mark=subst)
7   }
8 }
```

## Tree for "kicked the bucket"



```
1 class kicked_the_bucket
2 import nx0Vnx1[]
3 {
4     <syn>{
5         ?V [e=?X0] "kicked";
6         ?NP_Obj [] {
7             [cat=det] "the"
8             [cat=n] "bucket"
9         }
10    }
11 }
```

## Tree for "kicked the bucket"



```
1 class kicked_the_bucket
2 import nx0Vnx1[]
3 {
4     <syn>{
5         ?V [e=?X0] "kicked";
6         ?NP_Obj [] {
7             [cat=det] "the"
8             [cat=n] "bucket"
9         }
10    }
11 }
```

## Principles: motivation

- As fragments become more numerous, controlling their combination (and the scope of variables) gets difficult
- Idea: adding new constraints on top of dominance and precedence
- Principles: sets of additional constraints for the solver <sup>CrabbeDuchier:04</sup>

# A set of principles

XMG offers several sets of additional constraints over the models (principles):

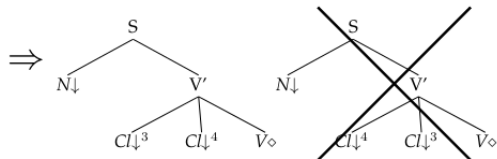
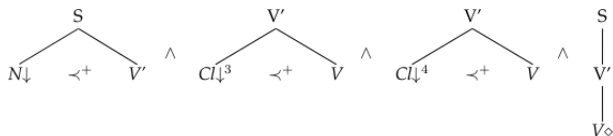
- colors: polarities for node unification
- rank: linear order constraints on nodes
- unicity: uniqueness of a feature inside a model



## Rank: Clitics ordering

- The ordering of clitic pronouns (in Spanish or French for example) is known to be problematic when formalizing a grammar
  - In a metagrammar, when combining fragments, nodes representing these clitics have to come in a specific order
- 
- Pedro nos la da
  - \*Pedro la nos da
  - Je le lui laisse
  - \*Je lui le laisse

## Rank: Clitics ordering (in French)



- Every produced model has to satisfy the order constraint

## Using principles: rank

```
1 use rank with () dims (syn)
2 type RANK=[1..7]
3 property rank: RANK

1 class CliticIobjectII
2 import nonReflexiveClitic[]
3 {
4   <syn>{
5     node xCl(rank=2)
6         [top=[func=iobj, pers = @{1,2}]]
7   }
8 }
```

## Using principles: unicity

```
1 use unicity with (rank=1) dims (syn)
2 use unicity with (rank=2) dims (syn)
3 use unicity with (rank=3) dims (syn)
4 use unicity with (rank=4) dims (syn)
5 use unicity with (rank=5) dims (syn)
6 use unicity with (rank=6) dims (syn)
7 use unicity with (rank=7) dims (syn)
```

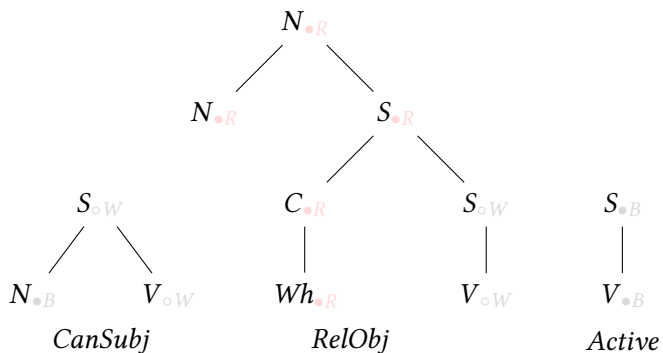
## Using principles: colors

- Colors are a solution to guide the combination of fragments
- A color is affected to every node
- New constraints on node unification

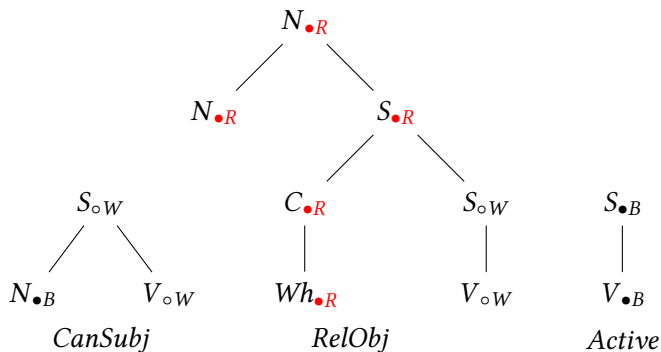
	● <sub>B</sub>	● <sub>R</sub>	○ <sub>W</sub>	⊥
● <sub>B</sub>	⊥	⊥	● <sub>B</sub>	⊥
● <sub>R</sub>	⊥	⊥	⊥	⊥
○ <sub>W</sub>	● <sub>B</sub>	⊥	○ <sub>W</sub>	⊥
⊥	⊥	⊥	⊥	⊥

- Valid models only have red and black nodes

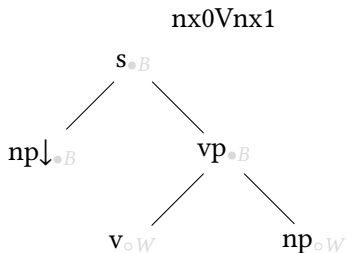
## Combination with polarities



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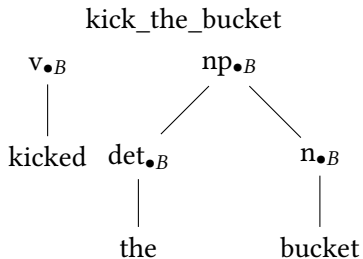
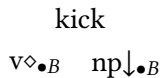
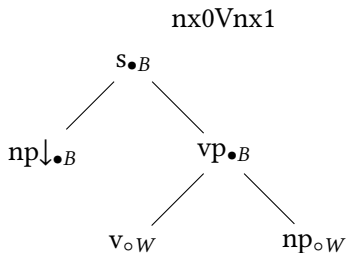
kick  
v◊.B    np↓.B

kick\_the\_bucket

```
graph TD; v1["v.B"] --- v2["v.B"]; v1 --- np["np.B"]; v2 --- kicked["kicked"]; np --- det["det.B"]; np --- n["n.B"]; det --- the["the"]; n --- bucket["bucket"];
```



# Combination with polarities



## Using principles: colors

```
1 use color with () dims (syn)
2 type COLOR={red,black,white}
3 property color: COLOR

1 class nx0Vnx1
2 declare ?S ?NP_Subj ?VP ?V ?NP_Obj
3 {
4   <syn>{
5     ?S (color=red)[cat=s] {
6       ?NP_Subj (color=black, mark=subst) [cat=np]
7       ?VP (color=black)[cat=vp] {
8         ?V (color=white)[cat=v]
9         ?NP_Obj (color=white)[cat=np]
10      }
11    }
12  }
13 }
```