Machine Learning for natural language processing Classification: *k* nearest neighbors

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Introduction

- Classification = supervised method for classifying an input, given a finite set of possible classes.
- Today: Vector-based document classification.

Jurafsky & Martin (2015), chapter 15, Jurafsky & Martin (2009) chapter 20 and Manning et al. (2008), chapter 14

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Motivation

- We can characterize documents by large vectors of real-valued features.
- Features are for instance words of a given vocabulary and their values reflect their occurrences in the document.
- This gives us a vector-space model of document classes.

Term-document matrix: Let *V* be our vocabulary, *D* our set of documents. A term-document matrix characterizing *D* with respect to *V* is a $|D| \times |V|$ where the cell for v_i and d_j contains the number of occurrences of v_i in d_i .

Each column in this matrix gives a vector of dimension |V| that represents a document.

This is again the bag-of-words representation of documents, except that V does not contain all words from the documents in D.

Example from Jurafsky & Martin (2015), chapter 19

Term-document matrix for four words in four Shakespeare plays:

	As You Like It	Twelth Night	Julius Caesar	Henry V
battle	1	1	8	15
soldier	2	2	12	36
fool	37	58	1	5
clown	5	117	0	0

In real applications, we usually have $10.000 \le |V| \le 50.000$.

General idea: Two documents are similar if they have similar vectors.

Example from Jurafsky & Martin (2015), chapter 19 continued



The above frequency counts are not the best measures for associations between terms and documents:

- A highly frequent word like *the* will not tell us anything about the class of a document since it occurs (more or less) equally frequent in all documents.
- Rare words also might be equally rare in all types of documents.
- The frequencies of such words, which are independent from the document class, should weigh less than the frequencies of words that are very typical for certain classes.

We need a weighting scheme that takes this into account.

A standard weighting scheme for term-document matrices in information retrieval is **tf-idf**:

tf-idf

- term frequency: tf_{td} = frequency of term t in document d. This can be simply the count of t in d.
- document frequency: *df_t* = number of documents in which term *t* occurs
- inverse document frequency: $idf_t = \log(\frac{|D|}{df_t})$
- tf-idf: $w_{td} = tf_{td}idf_t$

Terms occurring in lesser documents are more discriminative. Therefore their counts are weighted with a higher *idf* factor. Since |D| is usually large, we use the log of the inverse document frequency.

Note, however, that terms occurring in all documents get a weight 0.



Each document d is characterized with respect to a vocabulary $V=\{t_1,\ldots,t_{|V|}\}$ by a vector, for instance

 $\langle tf_{t_1,d}idf_{t_1},\ldots,tf_{t_{|V|},d}idf_{t_{|V|}}\rangle$

if we use tf-idf.

In order to compare documents, we need some metric for the distance of two vectors. One possibility is the **Euclidian distance**.

The length of a vector is defined as

$$\left|\vec{v}\right| = \sqrt{\sum_{i=1}^{n} v_i^2}$$

We define the Euclidian distance of two vectors \vec{v} , \vec{w} as

$$\left|\vec{v}-\vec{w}\right| = \sqrt{\sum_{i=1}^{n} (v_i - w_i)^2}$$

In order to use the Euclidian distance, we first have to normalize the vectors, i.e., we use

$$\frac{\vec{v}}{|\vec{v}|} - \frac{\vec{w}}{|\vec{w}|} = \sqrt{\sum_{i=1}^{n} (\frac{v_i}{|\vec{v}|} - \frac{w_i}{|\vec{w}|})^2}$$

Alternatively, we can also use a metric for the similarity of vectors.

The most common metric used in NLP for vector similarity is the **cosine** of the angle between the vectors.

Underlying idea: We use the dot product from linear algebra as a similarity metric: For vectors \vec{v} , \vec{w} of dimension *n*,

$$\vec{v} \cdot \vec{w} = \sum_{i=1}^{n} v_i w_i$$

Example: dot product

Consider the following term-document matrix:

	d_1	d_2	d_3	d_4
t_1	1	2	8	50
t_2	2	8	3	20
t_3	30	120	0	2

$$d_1, d_2: \vec{v}_{d_1} \cdot \vec{v}_{d_2} = \langle 1, 2, 30 \rangle \cdot \langle 2, 8, 120 \rangle = 3618$$

$$\bullet \ d_1, \ d_3: \ \vec{v}_{d_1} \cdot \vec{v}_{d_4} = 200$$

But:
$$\vec{v}_{d_2} \cdot \vec{v}_{d_4} = 500$$
 and $\vec{v}_{d_3} \cdot \vec{v}_{d_4} = 460$

The dot product favors long vectors. Therefore, we use the **normalized dot product**, i.e., we divide by the lengths of the two vectors.

Cosine similarity metric

$$CosSim(\vec{v}, \vec{w}) = \frac{\vec{v} \cdot \vec{w}}{|\vec{v}| |\vec{w}|} = \frac{\sum_{i=1}^{n} v_i w_i}{\sqrt{\sum_{i=1}^{n} v_i^2} \sqrt{\sum_{i=1}^{n} w_i^2}} = \cos \phi$$

where ϕ is the angle between \vec{v} and \vec{w} .

Reminder: This is how the cosine looks like for angles between 0 and 90 (with all vector components \geq 0, other angles cannot occur):



Example: cosine similarity

Consider again the following term-document matrix:

	d_1	d_2	d_3	d_4
t_1	1	2	8	50
t_2	2	8	3	20
t_3	30	120	0	2
$ \vec{v}_d $	30,08	120,28	8,54	53,89

Cosine values:

	d_1	d_2	d_3
d_2	1		
d_3	0.05	0.04	
d_4	0.09	0.08	1

(The cosine values for d_1 , d_2 and for d_3 , d_4 are rounded.)

Cosine similarity is not invariant to shifts.

Cosine



Adding 1 to all components increases the cosine similarity.

The Euclidian distance, however, remains the same (if used without normalization).

An alternative is the **Pearson correlation**:

Pearson correlation

Let $\overline{v} = \frac{\sum_{i=1}^{n} v_i}{n}$ be the means of the vector components.

$$Corr(\vec{v}, \vec{w}) = \frac{\sum_{i=1}^{n} (v_i - \overline{v})(w_i - \overline{w})}{|\vec{v} - \overline{v}| |\vec{w} - \overline{w}|} = CosSim(\vec{v} - \overline{v}, \vec{w} - \overline{w})$$

where $\langle v_1, \ldots, v_n \rangle - c = \langle v_1 - c, \ldots, v_n - c \rangle$.

Two other widely used similarity measures are **Jaccard** and **Dice**. The underlying idea is that we measure the overlap in the features. Therefore in both metrics, we include

$$\sum_{i=1}^n \min(v_i, w_i)$$

Jaccard similarity measure

simflaccard
$$(\vec{v}, \vec{w}) = \frac{\sum_{i=1}^{n} \min(v_i, w_i)}{\sum_{i=1}^{n} \max(v_i, w_i)}$$

Dice is very similar except that it does not take the max but the average in the denominator:

Dice similarity measure

$$simDice(\vec{v}, \vec{w}) = \frac{2\sum_{i=1}^{n} \min(v_i, w_i)}{\sum_{i=1}^{n} v_i + w_i}$$

In the following, we are concerned with the task of classifying a document by assigning it a label drawn from some finite set of labels.

Our training data consists of a set *D* of documents, each of which is in a unique class $c \in C$.

Documents are represented as vectors, i.e., our task amounts to classifying a new vector, given the classes of the training vectors.

Idea of k nearest neighbors (kNN): in order to classify a new document d, take the majority class of the k nearest neighbors of d in the training document vector space.

Exampl	le: i	k nearest neighbors	
		0	

Task: classify fictional texts in topic classes l (= <i>love</i>) and c (= <i>crime</i>).								
Training:	Class <i>l</i>		Class c		new docs:			
terms	d_1	d_2	d_3	d_4	d_5	d_6	d_7	
love	10	8	7	0	1	5	1	
kiss	5	6	4	1	0	6	0	
inspector	2	0	0	12	8	2	12	
murderer	0	1	0	20	56	0	4	
$ \vec{v_d} $	11.36	10.05	8.06	23.35	56.58	8.06	12.69	

Before comparing vectors, we should normalize them. (The definition of the cosine similarity above includes normalization.) I.e., every $\vec{v} = \langle v_1, \dots, v_n \rangle$ gets replaced with

$$\frac{\vec{v}}{|\vec{v}|} = \langle \frac{v_1}{|\vec{v}|}, \dots, \frac{v_n}{|\vec{v}|} \rangle \text{ where } |\vec{v}| = \sqrt{\sum_{i=1}^n v_i^2}$$

Example continued

Normalized data:

Training:	Class <i>l</i>		Class c		new docs:		
terms	d_1	d_2	d_3	d_4	d_5	d_6	d_7
love	0.88	0.8	0.87	0	0.02	0.62	0.08
kiss	0.44	0.6	0.5	0.04	0	0.74	0
inspector	0.18	0	0	0.51	0.14	0.25	0.95
murderer	0	0.1	0	0.86	0.99	0	0.32

Euclidian distances:

	d_1	d_2	d_3	d_4	d_5
d_6	0.4	0.35	0.43	1.3	1.38
d_7	1.24	1.35	1.37	0.7	1.05

Example continued

Visualization of the dimensions *love* and *murderer* including the *k* nearest neighbors of each of the new documents d_6 , d_7 for k = 1 and



For both *k*s, the majority class of the *k* nearest neighbors of d_6 is *l* while the one of d_7 is *c*.

Some notation:

- *S_k(d)* is the set of the *k* nearest neighbor documents of a new document *d*.
- $\vec{v}(d)$ is the vector of a document *d*.
- We define $I_c : S_k(d) \to \{0, 1\}$ for a class c and a document d as $I_c(d_t) = 1$ if the class of d_t is c, otherwise $I_c(d_t) = 0$.

Then kNN assigns the following score to each class c, given a document d that has to be classified:

$$score(c, d) = \sum_{d_t \in S_k(d)} I_c(d_t)$$

The classifier then assigns to d the class c from the set of classes C with the highest score:

$$\hat{c} = \underset{c \in C}{\operatorname{arg\,max}} \ score(c, d)$$

Choice of the *k*:

- usually an odd number;
- k = 3 or k = 5 are frequent choices but sometimes much larger values are also used;
- *k* can be choosen according to experiments during training on held-out data.

kNN can be used as a probabilistic classifier: We can define

$$P(c|d) = \frac{\sum_{d_t \in S_k(d)} I_c(d_t)}{k}$$

Example continued

		d_1	d_2	d_3	d_4	d_5
Euclidian distances:	d_6	0.4	0.35	0.43	1.3	1.38
	d_7	1.24	1.35	1.37	0.7	1.05

Probabilities:

$$k = 1 \quad S_1(d_6) = \{d_2\}, P(l|d_6) = 1, P(c|d_6) = 0$$

$$S_1(d_7) = \{d_4\}, P(l|d_7) = 0, P(c|d_7) = 1$$

$$k = 3 \quad S_3(d_6) = \{d_1, d_2, d_3\}, P(l|d_6) = 1, P(c|d_6) = 0$$

$$S_3(d_7) = \{d_1, d_4, d_5\}, P(l|d_7) = \frac{1}{3}, P(c|d_7) = \frac{2}{3}$$

Problem: For k > 1, the majority vote does not take the individual distances of the *k* nearest neighbors to $\vec{v}(d)$ into consideration.

Example

k = 5, classes *A* and *B*, document *d* has to be classified. Assume we have the following situation:



The classifier would assign *B*. But the two *A* documents in $S_5(d)$ are much nearer to *d* than the three *B* documents.

Possible solution: weight the elements in $S_k(d)$ be their similarity to d.

This gives the following revised definition of the score, including the cos similarity measure:

$$score(c,d) = \sum_{d_t \in S_k(d)} I_c(d_t) \cos(\vec{v}(d_t), \vec{v}(d))$$

where $\vec{v}(d)$ is the vector of some document *d*.

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